

On the regularity of weak solutions to refractor problem

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Abstract

In this note we derive the Monge-Ampère type equation in Euclidian coordinates describing the refraction phenomena of perfect lens. This simplifies the regularity issues of the weak solutions on the problem.

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1 Introduction and main result

It is well-known that ellipse and hyperbola have simple refraction properties, namely if rays of light diverge from one focus, then after refraction they pass parallel to the major axis [4]. If the ellipse (resp. hyperbola) represents the boundary separating two medias, with refractive indices n_1, n_2 then according to refraction law

$$n_1 \sin \alpha = n_2 \sin \beta,$$

where α and β are the angles between normal and respectively the ray before and after refraction. Let $k = n_1/n_2$, then one can verify that $k = 1/\varepsilon$, where ε is the eccentricity of ellipse (resp. hyperbola) [4]. These properties are limiting cases of solutions to more general problems of determining the surface required to refract rays of light diverging from one point and after refraction covering a given set of directions on the unit sphere. More precisely let us assume we are given two sets Ω, Ω^* on unit sphere centered at origin, and nonnegative integrable functions f, g defined respectively on Ω and Ω^* . Suppose that a point source of light is centered at the origin O and for every $X \in \Omega$ we issue a ray from O passing through X , which after refraction from the unknown surface Γ is another ray given by a unit direction

$Y = Y(X) \in \Omega^*$. It is clear that mapping Y is determined by Γ . Let $f(X)$ be the input intensity of light at $X \in \Omega$ and $g(Y)$ corresponding gain intensity after refraction at $Y \in \Omega^*$. Now the problem can be formulated as follows: given two pairs (Ω, f) and (Ω^*, g) satisfying to energy balance condition

$$\int_{\Omega} f = \int_{\Omega^*} g, \quad (1.1)$$

find a surface Γ , such that for corresponding mapping $Y(X)$ we have

$$Y(\Omega) = \Omega^*.$$

We seek a Γ as a radial graph of a unknown function ρ i.e. $\Gamma = \{Z \in \mathbf{R}^{n+1}, Z = X\rho(X)\}$, then mathematically this problem is amount to solve a Monge-Ampère type equation

$$\det(D_{ij}^2\rho - \sigma_{ij}(x, \rho, D\rho)) = h(x, \rho, D\rho), \quad (1.2)$$

subject to boundary condition

$$Y(\Omega) = \Omega^*. \quad (1.3)$$

Here the derivatives are taken in some orthogonal coordinate system (see Theorem 1) and Ω is a subset of upper half sphere. The solutions to (1.2), should be sought in the class of functions such that the matrix $D_{ij}^2\rho - \sigma_{ij}(x, \rho, D\rho) \geq 0$. It is easy to see that if $\rho \in C^2$ such that $D_{ij}^2\rho - \sigma_{ij} \geq 0$ then equation (1.2) is elliptic with respect to ρ .

It turns out that ρ is a potential function to an optimal transfer problem with a logarithmic cost function [1]

$$c(X, Y) = \begin{cases} \log \frac{1}{\varepsilon(X \cdot Y) - 1}, & \varepsilon > 1, X \cdot Y > k, \\ \log \frac{1}{1 - \varepsilon(X \cdot Y)}, & \varepsilon < 1, X \cdot Y < k. \end{cases}$$

A similar cost function appears in the reflector problem introduced by X-J. Wang [8], [9]. The regularity of the solutions to optimal transfer problems is discussed in [3] and [5]. The most important thing is the so-called A3 condition, imposed on matrix σ_{ij} [3]. As soon as one has it the rest of the regularity, both local and global will follow from the classical framework established in [3], [5] and [6]. In [1] authors have verified the A3 condition, however without using Euclidian coordinates.

In this note we give a simple way of verifying the A3 condition, for $k < 1$ without invoking to covariant derivatives. It is also explicit, strict and straightforward (3.4). Main idea is to find a simple formula for mapping $Y(X)$ using a parametrization of upper unit half sphere, used in [2]. Then the rest will follow along the arguments of [2]. This method is very general and one can apply it to *near-field* problem. Indeed if one considers a map $z = \rho x + ty$, where t is the stretch function, then $\det Dz$ will give the equation for near-field problem. However we don't discuss this problem in the present note. It is worth noting that, if support functions are ellipsoids, i.e. $k > 1$ the A3 condition is not fulfilled (see (3.4)).

1.1 Notations

Let us consider the case of two homogeneous medias, with refractive constants n_1 and n_2 . Ω and Ω^* are two domains on the unit sphere $\mathcal{S}^n = \{X = (x_1, \dots, x_{n+1}), x_1^2 + \dots + x_{n+1}^2 = 1\}$. For $X \in \mathcal{S}^n, x = (x_1, \dots, x_n, 0)$. We also suppose that Ω is a subset of upper unit sphere $\mathcal{S}_+^n = \mathcal{S}^n \cap \{x_{n+1} > 0\}$. In what follows we consider ρ as a function of $x \in \Omega_0$, with Ω_0 as orthogonal projection of Ω on to hyperplane $x_{n+1} = 0$. By $D\rho$ we denote the gradient of function ρ with respect to x variable $D\rho = (D_{x_1}\rho, \dots, D_{x_n}\rho, 0)$. The reciprocal of ρ is defined as $u = 1/\rho$. We also define two auxiliary functions $b = u^2 + |Du|^2 - (Du \cdot x)^2$ and $V = \sqrt{u^2 - \sigma b} + u$. In what follows $\sigma = (k^2 - 1)/k^2 = 1 - \varepsilon^2$.

1.2 The main results

Our main result is contained in the following

Theorem 1 *If ρ is the radial function defining Γ , and $u = 1/\rho$, then u is a weak solution to*

$$\det \left\{ \frac{V - \sigma(u - Du \cdot x)}{\sigma} \left(Id + \frac{x \otimes x}{1 - |x|^2} \right) - D^2u \right\} = h, \text{ if } k < 1, \quad (1.4)$$

$$\det \left\{ D^2u - \frac{V - \sigma(u - Du \cdot x)}{\sigma} \left(Id + \frac{x \otimes x}{1 - |x|^2} \right) \right\} = h, \text{ if } k > 1,$$

$$h = \frac{f(X)}{g(Y)} k \frac{\sqrt{u^2 - \sigma b}}{u} \frac{1}{(1 - |x|^2)} \left(\frac{V}{k|\sigma|} \right)^n,$$

where $b = u^2 + |Du|^2 - (Du \cdot x)^2, V = \sqrt{u^2 - \sigma b} + u$.

If we set $F = \sigma^{-1}(V - \sigma(u - Du \cdot x))$ and $I = Id + \frac{x \otimes x}{1 - |x|^2}$, the first fundamental form of the upper unit half sphere, then equation can be rewritten as $\det(IF - D^2u) = h$ for $k < 1$. The weak solutions for this equations can be defined through the theory of optimal transfers [1] (see [7] for the discussion of such problems). The higher regularity of the weak solutions depends on the properties of the function F . More precisely we have

Theorem 2 *If $k < 1$ (i.e. when the support functions are hyperboloids of revolution touching Γ from below) and (f, Ω) and (g, Ω^*) satisfy to the regularity assumptions as in [3], [5] and [6] then F is strictly concave as a function of the gradient and the weak solutions are locally (globally) smooth provided f, g are positive smooth functions and $\bar{\Omega}, \bar{\Omega}^* \subset \mathcal{S}_+^n$.*

If $k > 1$ (i.e. when the support functions are ellipsoids of revolution touching Γ from above) then F is not convex in gradient and the weak solutions may not be C^1 even for smooth positive intensities f, g .

2 The main formulas

In this section we derive a simple and useful formula for Y . We use it to compute the Jacobian determinant in the next section.

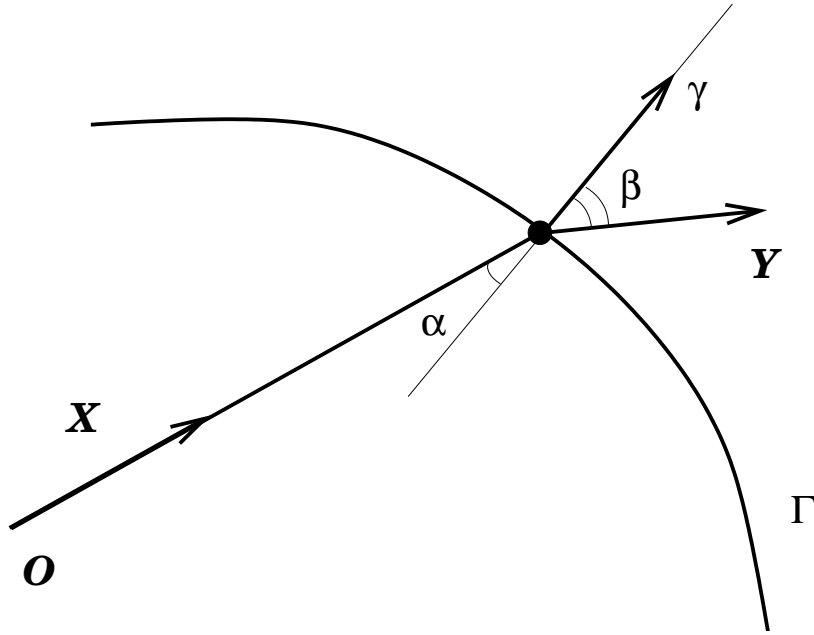


Figure 1: The refraction law.

2.1 The mapping Y

Let Y be the unit direction of the refracted ray. First let us derive a formula for Y , using angles α and β (see figure 1). Since X, Y and outward unit vector γ lie in the same plane, we have

$$Y = C_1 X + C_2 \gamma$$

for two unknowns, C_1 and C_2 depending on X . If one takes the scalar product of Y with γ and then with X , then

$$\begin{cases} \cos \beta = C_1 \cos \alpha + C_2 \\ \cos(\alpha - \beta) = C_1 + C_2 \cos \alpha. \end{cases}$$

Multiplying the first equation by $\cos \alpha$ and subtracting from the second one we infer

$$C_1 = \frac{\sin \beta}{\sin \alpha}, \quad C_2 = \cos \beta - C_1 \cos \alpha.$$

Introduce $k = n_1/n_2$, hence we find that $C_1 = k$ and $C_2 = \cos \beta - k \cos \alpha$, that is

$$Y = kX + (\cos \beta - k \cos \alpha)\gamma. \quad (2.1)$$

We can further manipulate (2.1). Note that

$$n_2^2 - n_2^2 \cos^2 \beta = n_2^2 \sin^2 \beta = n_1^2 \sin^2 \alpha = n_1^2 - n_1^2 \cos^2 \alpha.$$

Dividing the both sides by n_2^2 we obtain

$$k^2 \cos^2 \alpha = (k^2 - 1) + \cos^2 \beta.$$

Returning to (2.1) we get

$$\begin{aligned} Y &= kX + (\sqrt{k^2 \cos^2 \alpha - (k^2 - 1)} - k \cos \alpha) \gamma = \\ &= k \left(X + [\sqrt{(X \cdot \gamma)^2 - \sigma} - X \cdot \gamma] \gamma \right), \end{aligned} \quad (2.2)$$

where $\sigma = (k^2 - 1)/k^2$. From [2] we have

$$\gamma = -\frac{D\rho - X(\rho + D\rho \cdot x)}{\sqrt{\rho^2 + |D\rho|^2 - (D\rho \cdot x)^2}}$$

where $X = (x, \sqrt{1 - |x|^2})$, $D\rho = (\rho_{x_1}, \dots, \rho_{x_n})$. It is convenient to work with a new function $u = \rho^{-1}$. By direct computation we have that

$$\gamma = \frac{Du + X(u - Du \cdot x)}{\sqrt{u^2 + |Du|^2 - (Du \cdot x)^2}}.$$

Introduce $b = u^2 + |Du|^2 - (Du \cdot x)^2$, then

$$\begin{aligned} Y &= k \left(X + [\sqrt{(X \cdot \gamma)^2 - \sigma} - X \cdot \gamma] \gamma \right) \\ &= k \left(X + \left[\sqrt{\frac{u^2}{b} - \sigma} - \frac{u}{\sqrt{b}} \right] \gamma \right) \\ &= k \left(X + b^{-1} [\sqrt{u^2 - \sigma b} - u] [Du + X(u - Du \cdot x)] \right), \end{aligned}$$

where we used the fact that

$$X \cdot \gamma = \frac{u}{\sqrt{u^2 + |Du|^2 - (Du \cdot x)^2}} > 0.$$

In particular it follows from the previous formula that

$$Y_{n+1} = kX_{n+1} \left(1 - \frac{\sigma}{V} (u - (Du \cdot x)) \right). \quad (2.3)$$

2.2 The Jacobian determinant

Let dX and dY be respectively the area elements corresponding to Ω and Ω^* . Then $dx = X_{n+1}dX$. Recall that Y is a unit vector and denote $y = (Y_1, Y_2, \dots, Y_n, 0) \in \Omega_0^*$, where Ω_0^* is the orthogonal projection of Ω^* onto hyperplane $x_{n+1} = 0$ so we conclude $dy = Y_{n+1}dY$. Hence if we consider y to be a mapping from Ω_0 to Ω_0^* then $dy = |\det Dy| dx$.

For perfect refractor Γ we have the energy balance condition

$$\int_E f(X) dX = \int_{Y(E)} g(Y) dY, \quad \forall \text{ measurable } E \subset \Omega.$$

Thus we obtain $f dX = g dY$ or

$$J = \frac{X_{n+1}}{Y_{n+1}} |\det Dy| = \frac{f(X)}{g(Y)} = \frac{dX}{dY}. \quad (2.4)$$

Thus to find the Jacobian determinant J it is enough to compute $|\det Dy|$.

Before starting our computations let us note, that if $\mu = Id + C\xi \otimes \eta$ for some constant C and for any two vectors $\xi, \eta \in \mathbf{R}^n$, then one has

$$\mu^{-1} = Id - \frac{C\xi \otimes \eta}{1 + C(\xi \cdot \eta)}, \quad \det \mu = 1 + C(\xi \cdot \eta). \quad (2.5)$$

3 Proofs of Theorems 1-2

The main goal of this section is to prove the following

Proposition 1 *If Y is given as above and*

$$y = k \left[x - \frac{\sigma}{V} (Du + x(u - Du \cdot x)) \right],$$

then

$$Dy = k \frac{\sigma}{V} \mu [Id - x \otimes x] \left\{ \left(Id + \frac{x \otimes x}{1 - |x|^2} \right) \frac{V - \sigma(u - Du \cdot x)}{\sigma} - D^2 u \right\},$$

where $b = u^2 + |Du|^2 - (Du \cdot x)^2$, $V = \sqrt{u^2 - \sigma b} + u$ and μ is defined by (3.2).

Proof. Introduce $V = \sqrt{u^2 - \sigma b} + u$, $z = Du + x(u - Du \cdot x)$. Using these notations one can rewrite

$$y = k \left[x - \frac{\sigma}{V} z \right].$$

By a direct computation we have

$$\frac{y_{ij}}{k} = \delta_{ij} - \frac{\delta}{V} \left(z_j^i - \frac{z^i V_j}{V} \right).$$

Differentiating z^i and V with respect x_j yields

$$\begin{aligned} z_j^i &= u_{ij} - x_i x_m u_{m,j} + \delta_{ij} (u - Du \cdot x), \\ V_j &= p u_j - q (u_m - (Du \cdot x) x_m) u_{mj}, \end{aligned}$$

where

$$\begin{aligned} p &= \frac{V - \sigma(u - Du \cdot x)}{V - u}, \\ q &= \frac{\sigma}{V - u}. \end{aligned}$$

Then

$$\begin{aligned}
\frac{Dy}{k} &= Id - \frac{\sigma}{V} \left[(Id - x \otimes x) D^2 u + Id(u - Du \cdot x) - \frac{p}{V} z \otimes Du \right. \\
&\quad \left. + \frac{q}{V} z \otimes (Du - (Du \cdot x)x) D^2 u \right] \\
&= \left[1 - \frac{\sigma}{V}(u - Du \cdot x) \right] \left[Id + Az \otimes Du \right. \\
&\quad \left. - B \left\{ (Id - x \otimes x) + \frac{q}{V} z \otimes (Du - (Du \cdot x)x) \right\} D^2 u \right],
\end{aligned} \tag{3.1}$$

where we set

$$\begin{aligned}
A &= \frac{\frac{\sigma p}{V^2}}{1 - \frac{\sigma}{V}(u - Du \cdot x)} = \frac{\sigma}{V(V - u)}, \\
B &= \frac{\frac{\sigma}{V}}{1 - \frac{\sigma}{V}(u - Du \cdot x)} = \frac{\sigma}{V - \sigma(u - Du \cdot x)}.
\end{aligned}$$

Then using Lemma 1 (see below) we finally obtain

$$\begin{aligned}
\frac{Dy}{k} &= \left[1 - \frac{\sigma}{V}(u - Du \cdot x) \right] B \mu [Id - x \otimes x] \left\{ \left(Id + \frac{x \otimes x}{1 - |x|^2} \right) \frac{1}{B} - D^2 u \right\} \\
&= \frac{\sigma}{V} \mu [Id - x \otimes x] \left\{ \left(Id + \frac{x \otimes x}{1 - |x|^2} \right) \frac{1}{B} - D^2 u \right\} \\
&= \frac{\sigma}{V} \mu [Id - x \otimes x] \left\{ \frac{V - \sigma(u - Du \cdot x)}{\sigma} \left(Id + \frac{x \otimes x}{1 - |x|^2} \right) - D^2 u \right\}.
\end{aligned}$$

Hence to finish the proof of Proposition 1 it remains to prove

Lemma 1 *Let $\mu = Id + Az \otimes Du$, then*

$$\mu^{-1} \left\{ (Id - x \otimes x) + \frac{q}{V} z \otimes (Du - (Du \cdot x)x) \right\} = Id - x \otimes x, \tag{3.2}$$

$$\det \mu = \frac{Y_{n+1}}{k X_{n+1}} \frac{u}{\sqrt{u^2 - \sigma b}}. \tag{3.3}$$

Proof. First by (2.5)

$$\mu^{-1} = Id - \frac{Az \otimes Du}{1 + A(z \cdot Du)}.$$

Let $\mathcal{N} = \left\{ (Id - x \otimes x) + \frac{q}{V} z \otimes (Du - (Du \cdot x)x) \right\}$, then by a direct computation we have

$$\begin{aligned}
\mu^{-1} \mathcal{N} &= (Id - x \otimes x) + \frac{q}{V} z \otimes (Du - (Du \cdot x)x) - \frac{Az \otimes Du}{1 + A(z \cdot Du)} \\
&\quad + \frac{A}{1 + A(z \cdot Du)} \left[(Du \cdot x) z \otimes x - \frac{q}{V} (Du \cdot z) z \otimes (Du - (Du \cdot x)x) \right].
\end{aligned}$$

Let us sum up all \otimes products with z , the resulting vector is

$$\begin{aligned} \frac{q}{V}(Du - (Du \cdot x)x) + \frac{A}{1 + A(z \cdot Du)} \left\{ -Du + (Du \cdot x)x - \frac{q}{V}(Du \cdot z)(Du - (Du \cdot x)x) \right\} \\ = \left\{ \frac{q}{V} - \frac{A}{1 + A(z \cdot Du)} \left(1 + \frac{q}{V}Du \cdot z\right) \right\} (Du - (Du \cdot x)x). \end{aligned}$$

On the other hand

$$\frac{q}{V} - \frac{A}{1 + A(z \cdot Du)} \left(1 + \frac{q}{V}Du \cdot z\right) = \frac{1}{1 + A(z \cdot Du)} \left[\frac{q}{V} - A\right].$$

Using definitions of q, p and A we obtain that

$$\begin{aligned} \frac{q}{V} - A &= \frac{\sigma}{V(V - u)} - \frac{\sigma p}{V(V - \sigma(u - Du \cdot x))} \\ &= \frac{\sigma}{V} \left\{ \frac{1}{V - u} - \frac{\frac{V - \sigma(u - Du \cdot x)}{V - u}}{V - \sigma(u - Du \cdot x)} \right\} \\ &= 0. \end{aligned}$$

To prove (3.3) we notice that $A = \frac{\sigma}{V(V - u)}$. Then using (2.5) and $V = \sqrt{u^2 - \sigma b} + u$ we have

$$\begin{aligned} \det \mu &= 1 + \frac{\sigma}{V(V - u)} [|Du|^2 + u(Du \cdot x) - (Du \cdot x)^2] \\ &= \frac{1}{V(V - u)} [uV - u^2\sigma + \sigma u(Du \cdot x)] \\ &= \frac{u}{V - u} \left\{ 1 - \frac{\sigma}{V}(u - (Du \cdot x)) \right\} \end{aligned}$$

and (3.3) follows from (2.3). □

3.1 Ellipsoids and hyperboloids of revolution

In this section we show that $\mathcal{W} = IF - D^2u \equiv 0$ for $u = \frac{1}{C}(1 - \varepsilon(\ell \cdot X))$, that is when $\rho = 1/u$ is the radial graph of ellipsoid or hyperboloid of revolution. To fix ideas we assume that $\ell = e_{n+1}$. Thus $u = \frac{1}{C}(1 - \varepsilon X_{n+1})$. It is enough to show that $B = CX_{n+1}/\varepsilon$. By direct computation

$$\begin{aligned} b &= \frac{1}{C^2}(1 - 2\varepsilon X_{n+1} + \varepsilon^2) \\ u^2 - \sigma b &= \frac{\varepsilon^2}{C^2}(X_{n+1} - \varepsilon)^2. \end{aligned}$$

Therefore $V = (1 - \varepsilon^2)/C$, which implies that

$$B = \frac{\sigma}{V - \sigma(u - Du \cdot x)} = \frac{CX_{n+1}}{\varepsilon}.$$

3.2 Proof of Theorem 1

From Proposition 1, Lemma 1 and (2.5) we have that

$$\begin{aligned}\det Dy &= \left(k \frac{\sigma}{V}\right)^n \det \mu \det (Id - x \otimes x) \det \mathcal{W} \\ &= \left(k \frac{\sigma}{V}\right)^n \frac{Y_{n+1}}{k X_{n+1}} \frac{u}{\sqrt{u^2 - \sigma b}} (1 - |x|^2) \det \mathcal{W}\end{aligned}$$

where $\mathcal{W} = IF - D^2u$ i.e.

$$\mathcal{W} = \frac{V - \sigma(u - Du \cdot x)}{\sigma} \left(Id + \frac{x \otimes x}{1 - |x|^2} \right) - D^2u.$$

Notice that if Γ is smooth and has support hyperboloids from inside at each point then $\mathcal{W} \geq 0$ and $\mathcal{W} \leq 0$ if Γ has support ellipsoids from outside. Then from (2.4) the Theorem 1 follows.

3.3 Proof of Theorem 2

The equation (1.4) is generalized Monge-Ampère equation. To obtain smoothness of the solution, one needs to show, that $F = \frac{V - \sigma(u - Du \cdot x)}{\sigma}$ is strictly concave in gradient. This is a necessary condition, called A3 and first introduced in [3], in order to obtain C^2 a priori estimates. It turns out that if $\sigma < 0$, i.e. when support functions are hyperboloids of revolution, then F is strictly concave in gradient. Recall that $V = \sqrt{u^2 - \sigma b} + u$, hence it is enough to show that $\sqrt{u^2 - \sigma b}$ is convex in gradient. Let ξ be the dummy variable for Du , then we have

$$\begin{aligned}\frac{\partial}{\partial \xi_k} \sqrt{u^2 - \sigma b} &= -\frac{\sigma}{\sqrt{u^2 - \sigma b}} (\xi_k - (\xi \cdot x) x_k), \\ \frac{\partial^2}{\partial \xi_k \partial \xi_l} \sqrt{u^2 - \sigma b} &= -\frac{\sigma}{\sqrt{u^2 - \sigma b}} \left\{ \delta_{lk} - x_k x_l + \sigma \frac{(\xi_k - (\xi \cdot x) x_k)(\xi_l - (\xi \cdot x) x_l)}{u^2 - \sigma b} \right\}.\end{aligned}$$

On the other hand $b = u^2 + |\xi|^2 - (\xi \cdot x)^2$, which is strictly convex function of ξ , provided $|x| < 1$. For any $\eta \in \mathbf{R}^n$ we have

$$-(u^2 - \sigma b)^{\frac{3}{2}} \frac{\partial^2 F}{\partial \xi_k \partial \xi_l} \eta_k \eta_l = -(u^2 - \sigma b)^{\frac{3}{2}} \frac{1}{\sigma} \sum_{k,l} \frac{\partial^2 \sqrt{u^2 - \sigma b}}{\partial \xi_k \partial \xi_l} \eta_k \eta_l \quad (3.4)$$

$$= (u^2 - \sigma b) (|\eta|^2 - (\eta \cdot x)^2) + \sigma [\xi \cdot \eta - (\xi \cdot \eta)(\eta \cdot \xi)]^2$$

substituting the value of $b = |\xi|^2 - (\xi \cdot x)^2 + u^2$ we have

$$\begin{aligned}&= u^2(1 - \sigma) (|\eta|^2 - (\eta \cdot x)^2) + \\ &+ \sigma \left\{ -|\xi|^2 |\eta|^2 + |\xi|^2 (\eta \cdot x)^2 + |\eta|^2 (\xi \cdot x)^2 + (\xi \cdot \eta)^2 - 2(\xi \cdot \eta)(\xi \cdot x)(\eta \cdot x) \right\}.\end{aligned}$$

The first term is nonnegative since $|x| < 1$ and $(\eta \cdot x) \leq |\eta| |x| < |\eta|$. Recall that $\sigma < 0$. Hence it is enough to show that

$$-|\xi|^2 |\eta|^2 + |\xi|^2 (\eta \cdot x)^2 + |\eta|^2 (\xi \cdot x)^2 + (\xi \cdot \eta)^2 - 2(\xi \cdot \eta)(\xi \cdot x)(\eta \cdot x) < 0. \quad (3.5)$$

This expression is homogeneous in η and ξ thus we may assume that $|\xi| = |\eta| = 1$. Furthermore let x' be the orthogonal projection of x on the two dimensional space spanned by ξ and η . Then (3.5) is equivalent to

$$(\eta \cdot x')^2 + (\xi \cdot x')^2 + (\xi \cdot \eta)^2 - 2(\xi \cdot \eta)(\xi \cdot x')(\eta \cdot x') - 1 < 0.$$

If α, β and γ are the angles between respectively η and x' , ξ and x' and η and ξ then $\cos \gamma = \cos(\alpha \pm \beta)$. Thus we have

$$\begin{aligned} |x'|^2(\cos^2 \alpha + \cos^2 \beta - 2 \cos \alpha \cos \beta \cos \gamma) + \cos^2 \gamma - 1 < \\ (\cos^2 \alpha + \cos^2 \beta - 2 \cos \alpha \cos \beta \cos \gamma) + \cos^2 \gamma - 1 = 0. \end{aligned}$$

From here the proof of Theorem 1 follows from [3] and [6].

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